

EECS 245, Winter 2026

LEC 6

The Dot Product

Read: Ch. 3

Agenda

- Recap: linear combinations
- Dot Product
 - Definition
 - Properties
 - The "other" definition
 - Orthogonality
 - Inequalities (if time)

Read Ch. 3 this week!

3.1

3.3

Announcements

- HW 3 due Monday
- HW 4 released Monday, due following Monday
- HW 2 scores released
- Added more remote OH; still have OH after lecture

Example from last class

$\vec{x}, \vec{y} \in \mathbb{R}^3$

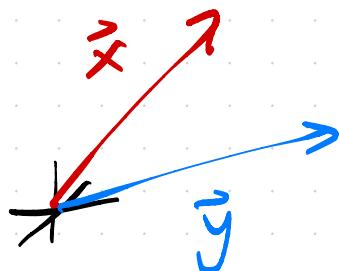
$$\vec{x} = \begin{bmatrix} 3 \\ -1 \\ 2 \end{bmatrix}$$

$$\vec{y} = \begin{bmatrix} 1 \\ 4 \\ 3 \end{bmatrix}$$

Goal: write $\vec{b} = \begin{bmatrix} 9 \\ -16 \\ -1 \end{bmatrix}$

as a **linear combination**

of \vec{x} and \vec{y} .



What does that mean?

$$\vec{b} = c\vec{x} + d\vec{y}$$

$\vec{v}_1, \vec{v}_2, \dots, \vec{v}_d \in \mathbb{R}^n$ "building blocks"

linear combination of them:

$$a_1 \vec{v}_1 + a_2 \vec{v}_2 + a_3 \vec{v}_3 + \dots + a_d \vec{v}_d$$

$$-2\vec{v}_1 + 3\vec{v}_2 - 6\vec{v}_3 + \vec{v}_4$$

$$\vec{x} = \begin{bmatrix} 3 \\ -1 \\ 2 \end{bmatrix}$$

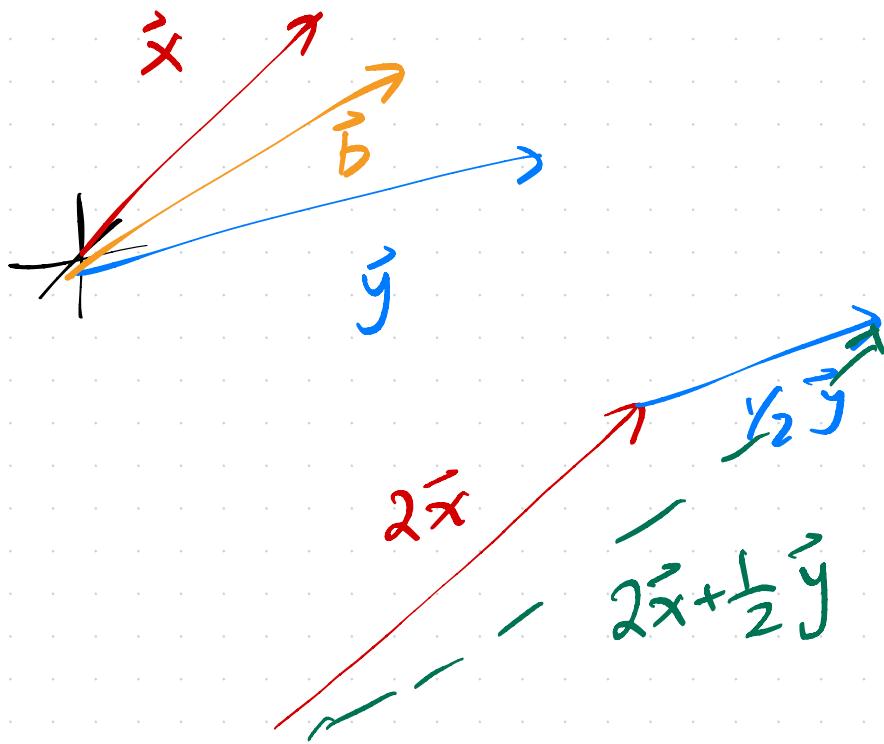
$$\vec{y} = \begin{bmatrix} 1 \\ 4 \\ 3 \end{bmatrix}$$

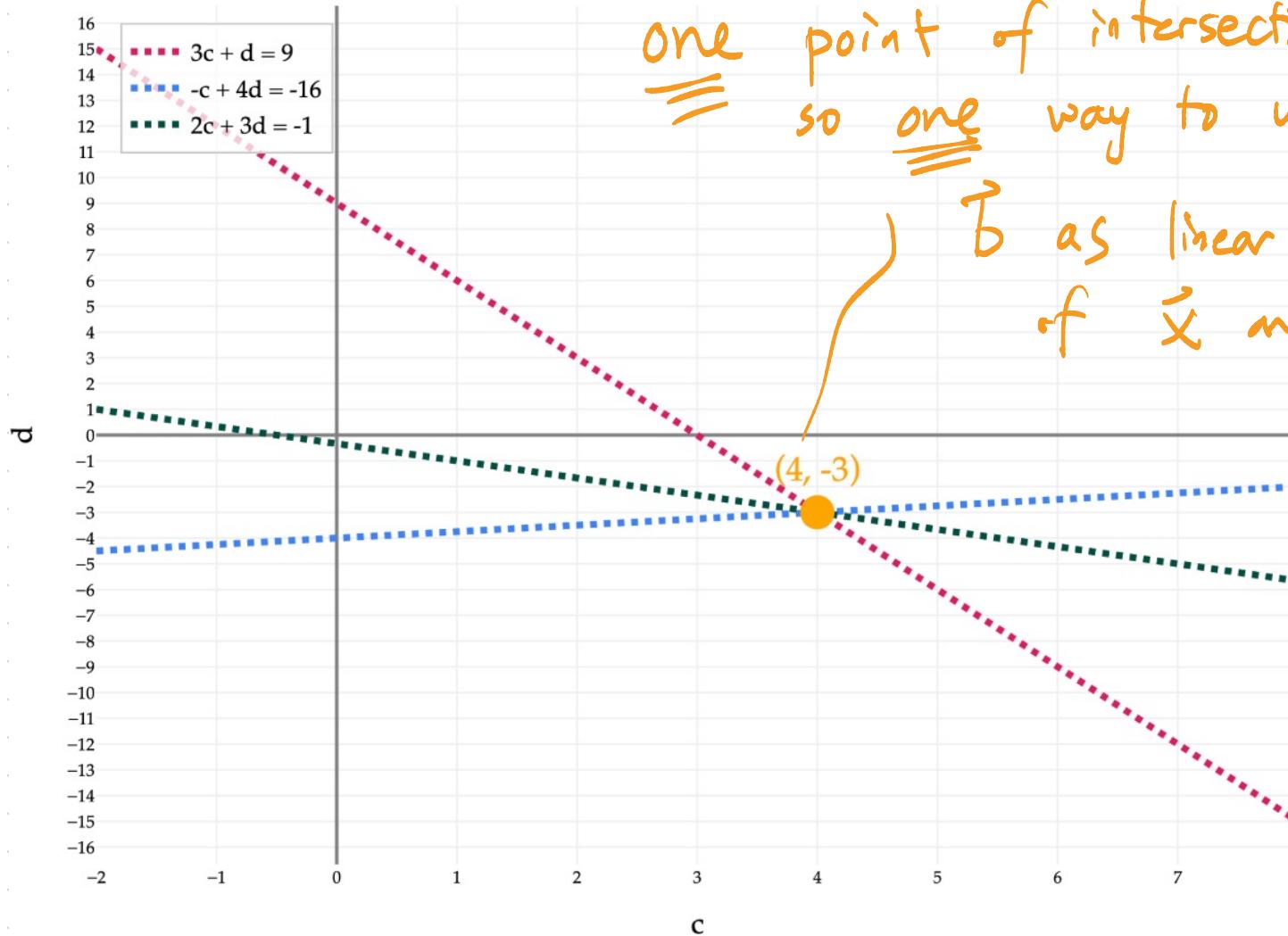
$$\vec{b} = \begin{bmatrix} 9 \\ -16 \\ -1 \end{bmatrix}$$

$$c\vec{x} + d\vec{y} = \vec{b}$$

$$c \begin{bmatrix} 3 \\ -1 \\ 2 \end{bmatrix} + d \begin{bmatrix} 1 \\ 4 \\ 3 \end{bmatrix} = \begin{bmatrix} 9 \\ -16 \\ -1 \end{bmatrix}$$

$$\begin{aligned} 3c + d &= 9 \\ -c + 4d &= -16 \\ 2c + 3d &= -1 \end{aligned} \quad \begin{array}{l} \rightarrow \text{solve for } c \text{ and } d! \\ \rightarrow \end{array}$$

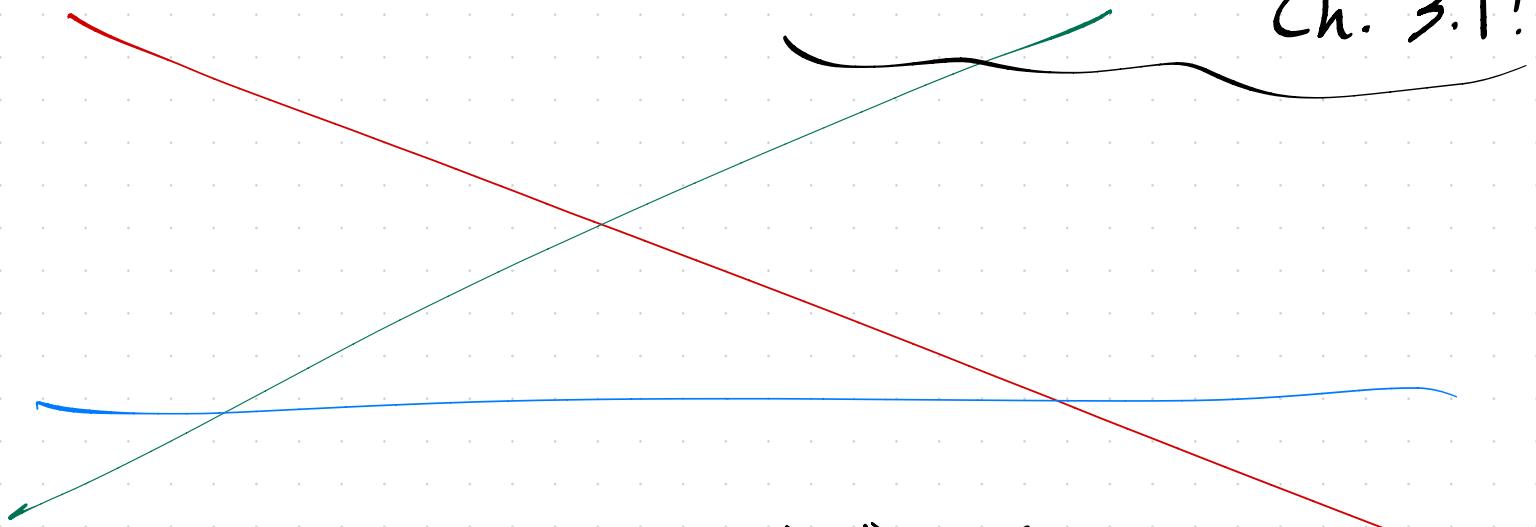




one point of intersection,
 \equiv so one way to write
 \vec{b} as linear comb.
of \vec{x} and \vec{y} !

look at the new pictures in

Ch. 3.1!



If my system looked like this,

then there would be no way to

write \vec{B} as a LC of \vec{x} and \vec{y} ! 

Dot product

$$\vec{u}, \vec{v} \in \mathbb{R}^n$$

same # of components

$$\vec{u} = \begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{bmatrix}$$

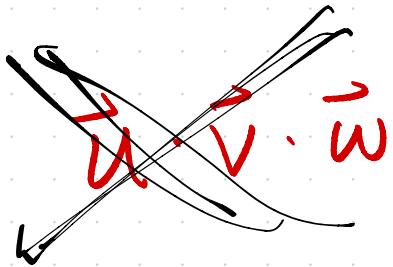
$$\vec{v} = \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix}$$

returns a scalar!

$$\vec{u} \cdot \vec{v} = \underbrace{u_1 v_1 + u_2 v_2 + \dots + u_n v_n}_{2 \text{ vectors}} = \vec{v} \cdot \vec{u}$$

$$\vec{x} = \begin{bmatrix} 4 \\ 3 \end{bmatrix} \quad \vec{y} = \begin{bmatrix} -2 \\ -5 \end{bmatrix}$$

$$\vec{x} \cdot \vec{y} = (4)(-2) + (3)(-5) = -23$$

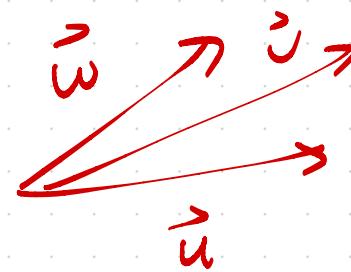


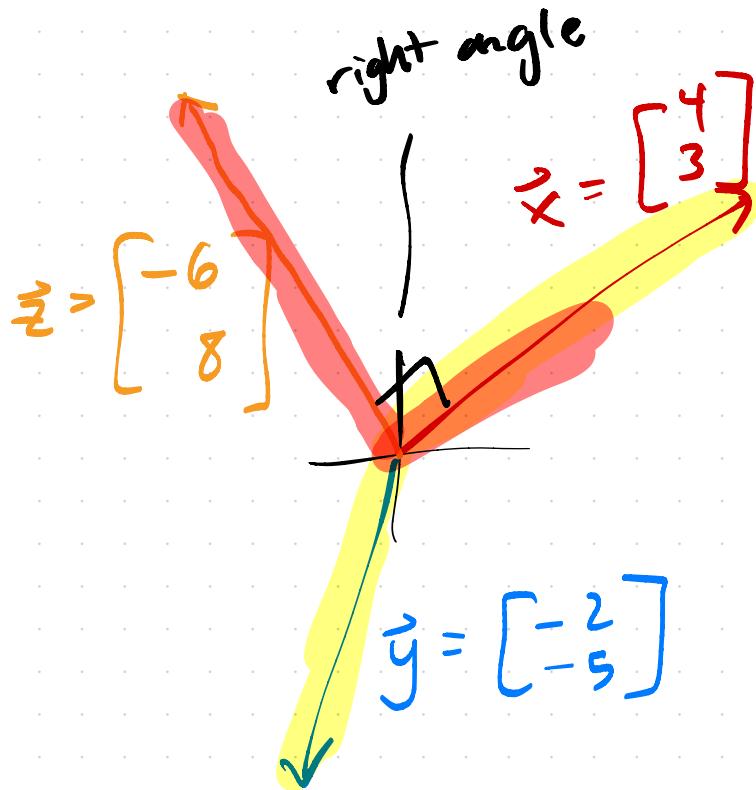
not defined!

$$(\vec{u} \cdot \vec{v}) \vec{w} \quad \text{is defined!}$$

$$\vec{u} (\vec{v} \cdot \vec{w})$$

$$= (\vec{v} \cdot \vec{w}) \vec{u}$$





$$\vec{x} \cdot \vec{z} = \vec{z} \cdot \vec{x} = (-6)(4) + (8)(3) = 0$$

$$\vec{x} \cdot \vec{y} = -23$$

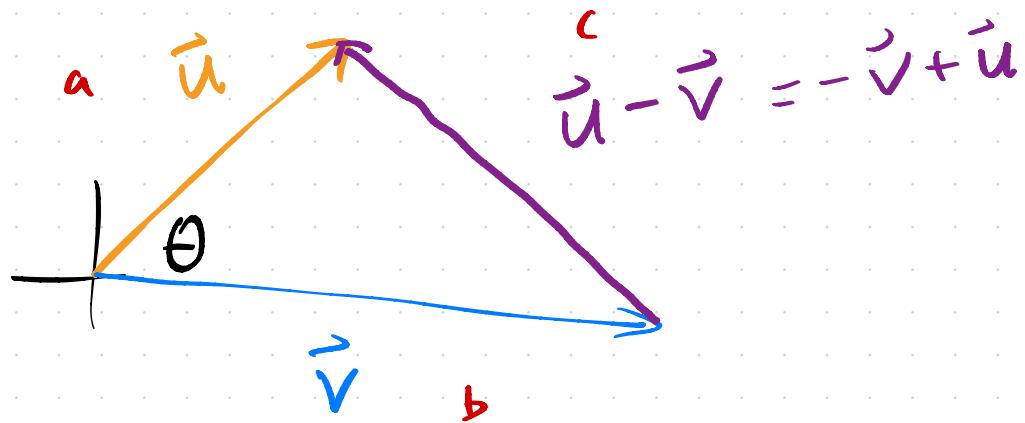
$$\begin{aligned}\vec{x} \cdot \vec{x} &= (4)(4) \\ &+ (3)(3) \\ &= 25\end{aligned}$$

"orthogonal"
"perpendicular"

key idea: dot product
measures

SIMILARITY

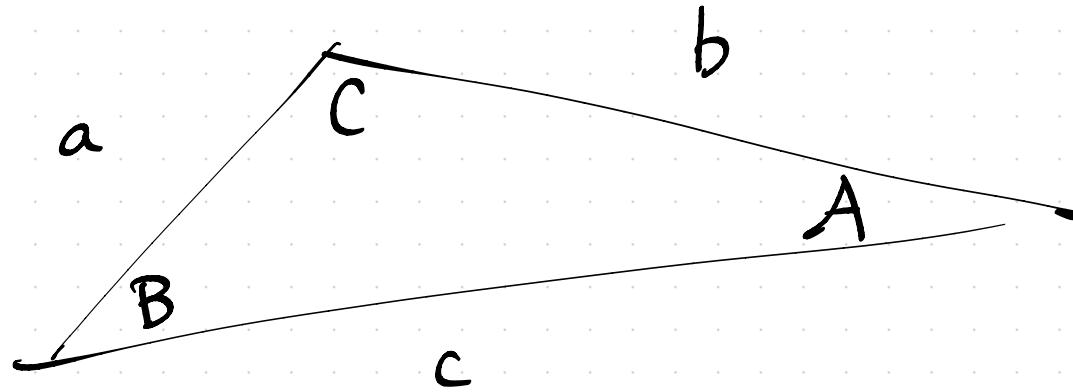
between vectors



general: $c^2 = a^2 + b^2 - 2ab \cos(C)$

$$\|\vec{u} - \vec{v}\|^2 = \|\vec{u}\|^2 + \|\vec{v}\|^2 - 2\|\vec{u}\|\|\vec{v}\| \cos \theta$$

Aside: cosine law!



$$c^2 = a^2 + b^2 - 2ab \cos(C)$$

$$a^2 = b^2 + c^2 - 2bc \cos(A)$$

Aside :

$$\vec{v} \cdot \vec{v} = \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix} \cdot \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix}$$

$$\vec{v} \cdot \vec{v} = \|\vec{v}\|^2$$

$$\begin{aligned} &= (v_1)(v_1) + (v_2)(v_2) + \dots + (v_n)(v_n) \\ &= v_1^2 + v_2^2 + \dots + v_n^2 \\ &= \|\vec{v}\|^2 \end{aligned}$$

we've discovered:

$$\|\vec{u} - \vec{v}\|^2 = \|\vec{u}\|^2 + \|\vec{v}\|^2 - 2\|\vec{u}\|\|\vec{v}\|\cos\theta$$

$$\|\vec{u} - \vec{v}\|^2 = (\vec{u} - \vec{v}) \cdot (\vec{u} - \vec{v})$$

equal!

$$= \underbrace{\vec{u} \cdot \vec{u}}_{\|\vec{u}\|^2} - \underbrace{\vec{u} \cdot \vec{v}}_{\|\vec{u}\|\|\vec{v}\|\cos\theta} - \underbrace{\vec{v} \cdot \vec{u}}_{\|\vec{u}\|\|\vec{v}\|\cos\theta} + \underbrace{\vec{v} \cdot \vec{v}}_{\|\vec{v}\|^2}$$

$$= \|\vec{u}\|^2 + \|\vec{v}\|^2 - 2\vec{u} \cdot \vec{v}$$

$$\cancel{\|\vec{u}\|^2 + \|\vec{v}\|^2} \cancel{- 2\|\vec{u}\|\|\vec{v}\|\cos\theta} = \|\vec{u}\|^2 + \|\vec{v}\|^2 \cancel{- 2\vec{u} \cdot \vec{v}} \cancel{- 2}$$

⇒

$$\vec{u} \cdot \vec{v} = \|\vec{u}\| \|\vec{v}\| \cos \theta$$

$$= u_1 v_1 + u_2 v_2 + \dots + u_n v_n$$

"geometric
definition"



$$\cos 90^\circ = 0$$

$$\vec{u} \cdot \vec{v} = \|\vec{u}\| \|\vec{v}\| \cos \theta$$

$$\Rightarrow \cos \theta = \frac{\vec{u} \cdot \vec{v}}{\|\vec{u}\| \|\vec{v}\|}$$

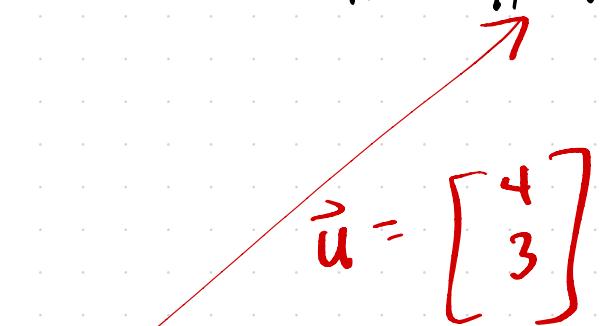
$$-1 \leq \cos \theta \leq 1$$

“cosine similarity” of 2 vectors

$$\theta = 0, \cos \theta = 1$$

$$\theta = 180, \cos \theta = -1$$

$$\cos \theta = \frac{\vec{u} \cdot \vec{v}}{\|\vec{u}\| \|\vec{v}\|} = \left(\frac{\vec{u}}{\|\vec{u}\|} \right) \cdot \left(\frac{\vec{v}}{\|\vec{v}\|} \right)$$

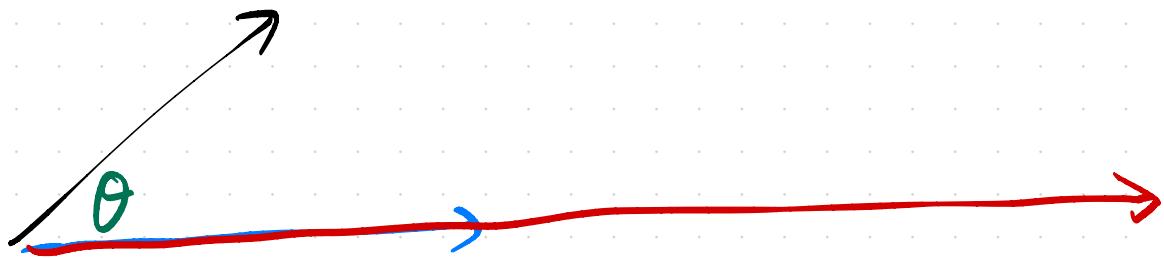


"unit vector"

$$\vec{u} = \begin{bmatrix} 4 \\ 3 \end{bmatrix}$$

$$\frac{\vec{u}}{\|\vec{u}\|} = \begin{bmatrix} 4/5 \\ 3/5 \end{bmatrix}$$

Same direction as \vec{u} !



Aside :

"default" $\|\vec{v}\|_2 = \sqrt{v_1^2 + v_2^2 + \dots + v_n^2}$ "L₂"

$$\|\vec{v}\|_1 = |v_1| + |v_2| + \dots + |v_n| \quad \text{"L}_1\text{"}$$

$$\vec{v} = \begin{bmatrix} -3 \\ 2 \\ 1 \end{bmatrix}$$

$$\|\vec{v}\|_\infty = \max \text{ absolute value of any component} \quad \text{"L}_\infty\text{"}$$

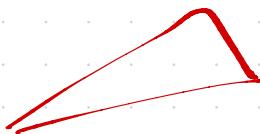
$$\|\vec{v}\|_\infty = 3$$

Two important inequalities

assume (as usual)
the L_2 norm

① Triangle inequality

$$\|\vec{u} + \vec{v}\| \leq \|\vec{u}\| + \|\vec{v}\|$$



② Cauchy-Schwarz

$$|\vec{u} \cdot \vec{v}| \leq \|\vec{u}\| \|\vec{v}\|$$

~~ex~~
Prove that the geometric mean of a, b \leq arithmetic mean of a, b

want to show:

$$\sqrt{ab} \leq \frac{a+b}{2}$$

hint: use C-Z inequality

$$\vec{u} = \begin{bmatrix} \sqrt{a} \\ 1 \end{bmatrix} \quad \vec{v} = \begin{bmatrix} \sqrt{b} \\ 1 \end{bmatrix}$$