

## EECS 245 Fall 2025 Math for ML

Lecture 8: Spans and Linear Independence

-> Read: Ch. 2.4 (new!)

open notes directly from Agenda notes. eecs 245. org ; direct links broken rn In general, given d'vectors in IR?, what can we make with their linear combinations?

Ch. 2.4

(2) Linear independence

"Three Questions" linear combinations

Given V., Jz,..., Ja EIR", and BER" d vectors n components each

Can we write b as a linear combination of

i.e. is there  $a_1\vec{v}_1 + \alpha_2\vec{v}_2 + - + \alpha_d\vec{v}_d = \vec{b}$ ?

a solution for

The the  $a_1\vec{v}_3$  unique?

- 3 Span

span  $(5\sqrt{1}, \sqrt{2}, \sqrt{1}) = \text{set of all possible linear combinations of } \sqrt{1}, \sqrt{2}, -.., \sqrt{d}$ 

span 
$$(2\sqrt{1}, 2\sqrt{2})$$
 combinations of  $\sqrt{1}, \sqrt{2}, -\sqrt{1}$ 

$$= \begin{cases} a_1\sqrt{1} + a_2\sqrt{2} + - + a_d\sqrt{d} \end{cases} \begin{vmatrix} a_1, a_2, - \\ \in R \end{vmatrix}$$

 $= \left\{ a_1 \overline{V_1} + a_2 \overline{V_2} + \dots + a_d \overline{V_d} \middle| \begin{array}{l} a_1, a_2, \dots, a_d \\ \in \mathbb{R} \end{array} \right.$ condition for inclusion

Aside: lines are 1-dimensional

$$\mathbb{R}^2$$
  $y = 4x-7$ 
 $\mathbb{R}^3$   $\mathbb{R}^4$ , parametric

form

 $L = \begin{bmatrix} 1 \\ 2 \\ -4 \end{bmatrix} + t \begin{bmatrix} -3 \\ 6 \end{bmatrix}$ 

span of 2 vectors

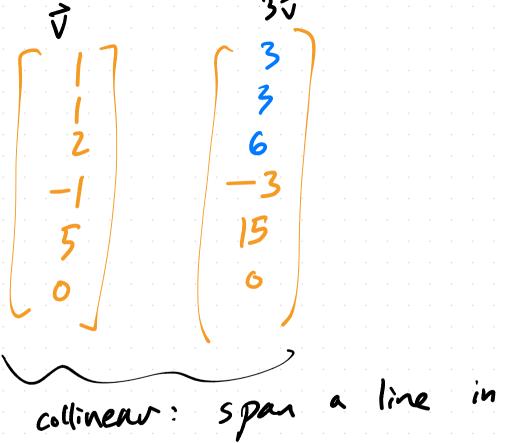
e.x. 
$$IR^2$$
 $\vec{v}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ 
 $\vec{v}_2 = \begin{bmatrix} 2 \\ 2 \end{bmatrix}$ 

$$\vec{V}_1 = \begin{bmatrix} \vec{V}_2 & \vec{V}_2 \\ \vec{V}_3 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_2 & \vec{V}_2 \\ \vec{V}_3 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_2 & \vec{V}_3 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_2 & \vec{V}_3 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_2 & \vec{V}_3 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_2 & \vec{V}_3 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_2 & \vec{V}_3 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_3 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_3 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_3 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_4 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_4 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_4 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_4 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_4 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_4 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_4 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_4 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_4 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_4 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_4 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_4 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_4 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_4 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_4 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_4 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_4 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_4 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_4 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_4 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_4 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_4 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_4 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_4 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_4 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_4 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_4 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_4 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_4 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_4 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_4 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_4 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_4 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_4 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_4 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_4 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_4 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_4 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_4 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_4 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_4 \end{bmatrix} = \begin{bmatrix} \vec{V}_4 & \vec{V}_4 \\ \vec{V}_4 & \vec{V}_$$

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2 vectors in R2, not coliner

$$\frac{1\vec{v}_1 + (1.2)\vec{v}_2}{3\vec{v}_1 + (-1)\vec{v}_2}$$

$$span\left(\left(\frac{\vec{v}_1}{\vec{v}_2}, \frac{\vec{v}_2}{\vec{v}_2}\right)\right) = \mathbb{R}^2$$

$$\frac{-3\vec{v}_1 + (0.75)\vec{v}_2}{3\vec{v}_1 + (0.75)\vec{v}_2}$$

$$for any  $\vec{b} \in \mathbb{R}^2$ 

$$solution exists$$

$$a_1\vec{v}_1 + a_2\vec{v}_2 = \vec{b}$$

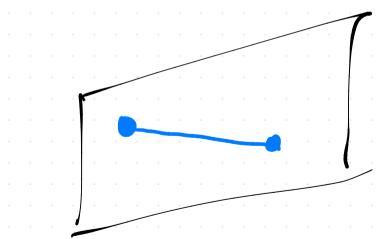
$$unique, fool$$$$

V, V2 not 2 vectors in R3. as long as salar multiples of each other,  $span(\{\vec{v}_1,\vec{v}_2\}) = plane$ = 2-dimensional "slice" of 1123

$$\vec{V}_1 = \begin{bmatrix} 5 \\ 2 \\ 1 \end{bmatrix} \qquad \vec{V}_2 = \begin{bmatrix} -2 \\ 3 \\ 6 \end{bmatrix}$$

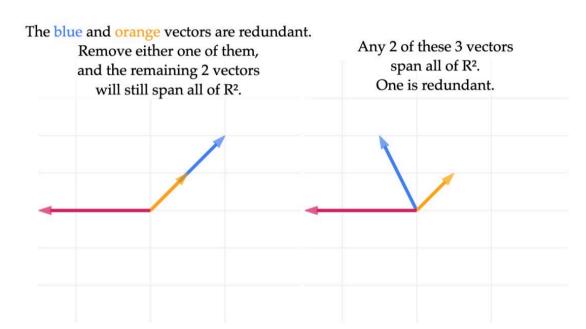
any point on the plane that  $= a_1 \begin{bmatrix} 5 \\ 2 \\ 1 \end{bmatrix} + a_2 \begin{bmatrix} -2 \\ 3 \\ 0 \end{bmatrix}$ Vi and Vi think of (a,, a2) "New" coordinates for the plane

plane: pick any two points on the plane. the line connecting them is entirely on the plane



2 vectors in IR" ? 2 (non-collinear) vectors in R<sup>n</sup> span a d-dimensional subspace of IR" flat object that passes through (0,0,...)
and contains of linear combinations
of some set of
vectors uslice

$$\vec{V}_1 = \begin{bmatrix} 5 \\ 1 \\ 2 \\ 2 \end{bmatrix}$$
 $\vec{V}_2 = \begin{bmatrix} 3 \\ 3 \\ 5 \end{bmatrix}$ 
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 $\vec{V}_4 = \begin{bmatrix} 5$ 



3 vectors in R<sup>2</sup>
possibilities

مد

- plane

12 = -21 - Tz Activity Given that  $\vec{b} = 2\vec{v_1} + 3\vec{v_2} - 4\vec{v_3} + 2\vec{v_2} - 2\vec{v_2}$ unite b as a linear combination where coefficient on

vectors in R 3d subspoce that a spon 2 | 1 | 1 | 0

Linear independence

J1, J2, --, va are linearly independent if none of the vectors are a linear combination of other vectors in the set otherwise, they we linearly dependent i) alternative definition Vi, Vw ---, va linearly independent if the only way to create o as a linear combination is Ov, +0 v2 +-- +0 va.

 $\vec{V}_1 = \frac{2}{3}\vec{V}_2 - 7\vec{V}_3$  $\vec{v_1} - \frac{2}{3}\vec{v_2} + 7\vec{v_3} = 0$ linearly dependent