

EECS 245, Winter 2026

LEC 10 Basis and Dimension

→ Read: Ch. 4.3

Agenda

all in scope
✓

- Review subspaces
- Basis and dimension
- If time: orthogonal complements

Announcements

- Midterm 1 Monday 7-9PM!
- HW 5 due Friday
- Grade Report updated
- Mock exam on Friday, 10/4 DOW 2:30-5:30 PM
- Lecture on Monday will be office hours (in lec room)
- See videos for FA25 Midterm 1

Two big ideas

① what makes a subset of \mathbb{R}^n a subspace?

② span \longleftrightarrow subspace

↓
given $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_d$,
describe the subspace
they span

↓
given a description of a
subspace S , find vectors
 $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_d$ such that
 $\text{span}(\{\vec{v}_1, \dots, \vec{v}_d\}) = S$

multiply by my scalar, and
you're no longer
on the curve!

not a
subspace

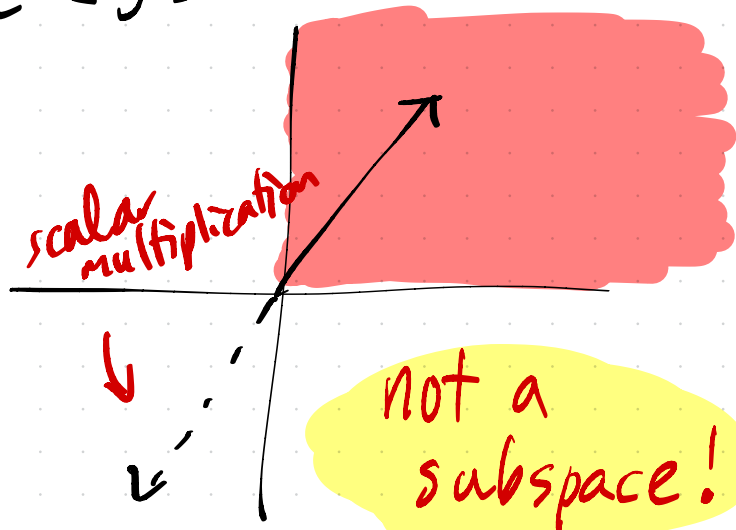
needs to
pass through
here

\mathbb{R}^2



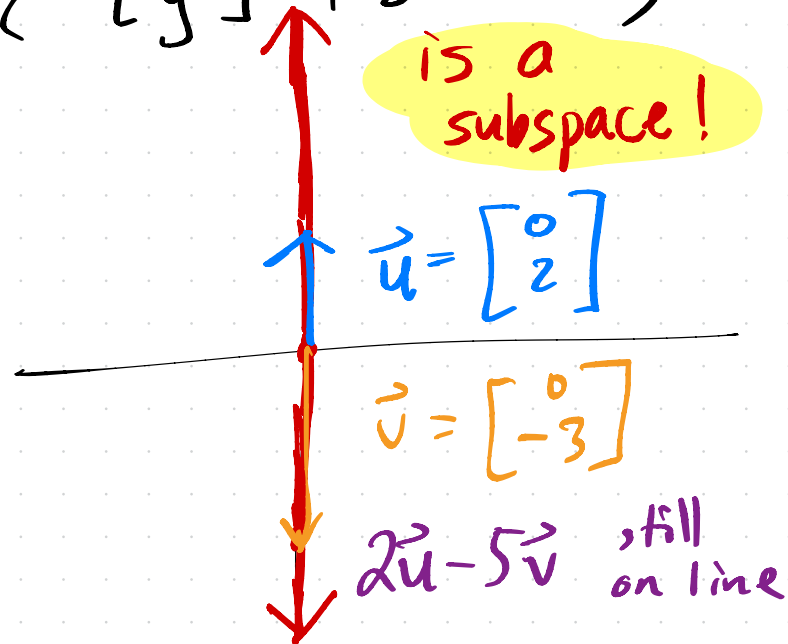
set of all vectors in \mathbb{R}^2
where BOTH components
are ≥ 0

$$\left\{ \begin{bmatrix} x \\ y \end{bmatrix} \mid x \geq 0, y \geq 0 \right\}$$



set of all vectors in \mathbb{R}^2
whose first component
is 0

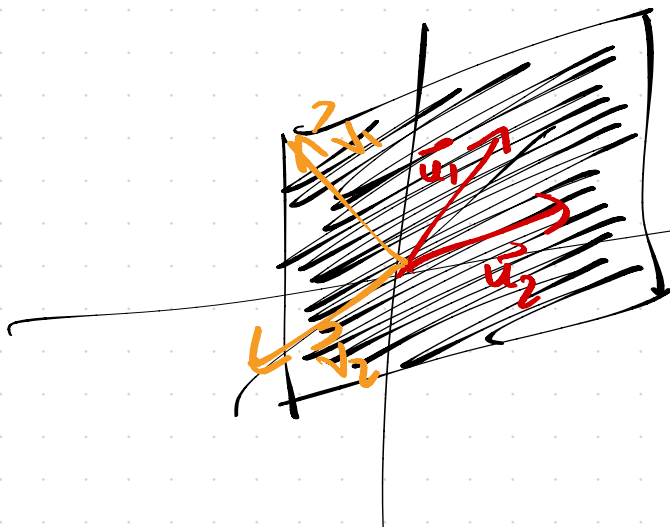
$$\left\{ \begin{bmatrix} 0 \\ y \end{bmatrix} \mid y \in \mathbb{R} \right\}$$



$$x+y+z=0$$

plane in \mathbb{R}^3

this is a subspace!



$$\text{span} \left(\left\{ \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix} \right\} \right)$$

\vec{u}_1 \vec{u}_2 basis

$$\text{span} \left(\left\{ \begin{bmatrix} 2 \\ 1 \\ -3 \end{bmatrix}, \begin{bmatrix} 99 \\ -98 \\ -1 \end{bmatrix} \right\} \right) = \text{basis}$$

\vec{v}_1 \vec{v}_2

$$\left\{ \begin{bmatrix} x \\ y \\ z \end{bmatrix} \mid x+y+z=0 \right\}$$

same thing

big idea:

- the span of a set of vectors is a subspace
- all subspaces can be written as the span of some set of vectors

Basis

bases : plural of basis

Dimension

$\dim(S)$

is the number
of vectors
in any basis
for S

A basis for a subspace S is
a set of vectors that:

- are linearly independent, and
- span all of S

basis is a minimal set of
"building blocks" (spanning vectors)

→ every subspace has infinitely many
bases!

$$2x - 3y + 4z = 0$$

① 2 possible bases

② dimension

$$\dim(S) = 2$$

$$- \left\{ \begin{bmatrix} -7 \\ 2 \\ 5 \end{bmatrix}, \begin{bmatrix} -3 \\ 6 \\ 6 \end{bmatrix} \right\}$$

one of infinitely many
bases

$$- \left\{ \begin{bmatrix} 3 \\ 2 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 4 \\ 3 \end{bmatrix} \right\}$$

another possibility

Aside: Parametric equation for a plane

$$P: s \begin{bmatrix} -7 \\ 2 \\ 5 \end{bmatrix} + t \begin{bmatrix} -3 \\ 6 \\ 6 \end{bmatrix}, s, t \in \mathbb{R}$$

e.g. a 3d subspace in \mathbb{R}^6

$$s \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \\ 5 \\ 6 \end{bmatrix} + t \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \\ 0 \\ 1 \end{bmatrix} + u \begin{bmatrix} 3 \\ 4 \\ 5 \\ -17 \\ 32 \\ \pi^2 \end{bmatrix}, s, t, u \in \mathbb{R}$$

Aside: "Standard" basis for \mathbb{R}^n

e.g. \mathbb{R}^2

$$\left\{ \begin{bmatrix} \pi \\ 7 \end{bmatrix}, \begin{bmatrix} -2 \\ e \end{bmatrix} \right\}$$

a basis

$$\left\{ \begin{bmatrix} 3 \\ 4 \end{bmatrix}, \begin{bmatrix} 4 \\ -3 \end{bmatrix} \right\}$$

orthogonal basis

$$\left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}$$

standard basis

$$\begin{bmatrix} 7 \\ -3 \end{bmatrix} = 7 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + (-3) \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

Why do we care about linear independence?

→ When vectors are linearly independent,
any linear combination of them
can only be written in one way!

e.g. $\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 3 \\ 4 \\ 0 \end{bmatrix} \right\}$

\vec{u} \vec{v} \vec{w}

not a basis, but they span all of \mathbb{R}^2 !

key: if vectors are not LI,
any linear combination of them
can be expressed infinitely many
ways
→ bad!

$$\vec{x} = 2\vec{u} + 3\vec{v} + \vec{w}$$

$$\begin{aligned} \vec{x} &= (2 - 1.72 \times 3) \vec{u} \\ &\quad + (3 - 1.72 \times 4) \vec{v} \\ &\quad + 2.72 \vec{w} \end{aligned}$$

$$\vec{w} = 3\vec{u} + 4\vec{v}$$

$$\vec{0} = 3\vec{u} + 4\vec{v} - \vec{w}$$

$$(-1.72) \vec{0} = (-1.72) 3\vec{u}$$

nothing
special
about
-1.72

$$\begin{aligned} &+ (-1.72) 4\vec{v} \\ &+ 1.72 \vec{w} \end{aligned}$$

$$\left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right\}$$

→ span is a
3-dimensional
subspace of \mathbb{R}^4

→ they are a basis for
that subspace

- ① is this a basis for \mathbb{R}^4 ? no: only 3 vectors
- ② dimension of their span? 3
- ③ are they linearly independent? yes

$$\left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 6 \\ -6 \\ 0 \\ 14 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 3 \\ 3 \\ 7 \end{bmatrix} \right\}$$

- ① is this a basis for \mathbb{R}^4 ? no
- ② dimension of their span? 3
- ③ are they linearly independent? no

orthogonal complement: see 4.3