



EECS 245 Fall 2025

Math for ML

Lecture 14: Inverses, Projections

→ Read : Ch 2.9 (new examples added!)
Ch 2.10 (in progress)

Agenda

- ① Recap: Inverses (review of last lecture and lab)
- ② Projecting onto the span of multiple vectors

↓ final idea before we go
back to "core"
machine learning!

Announcements:

- ① HW 6 due **Monday** → do it, don't drop it!
- ② Check the "Grade Report" on Gradescope

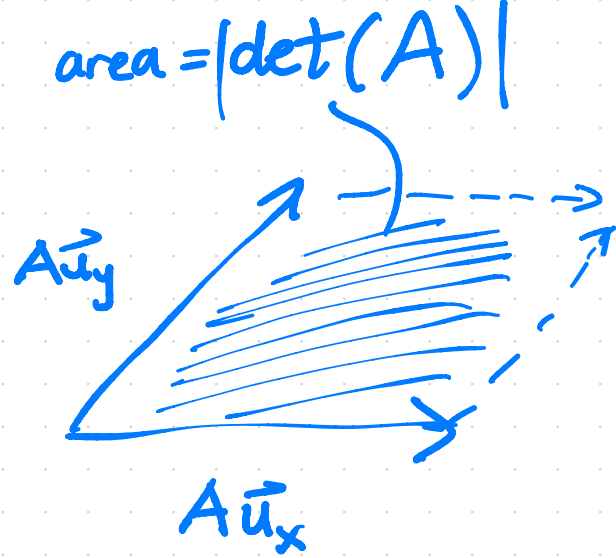
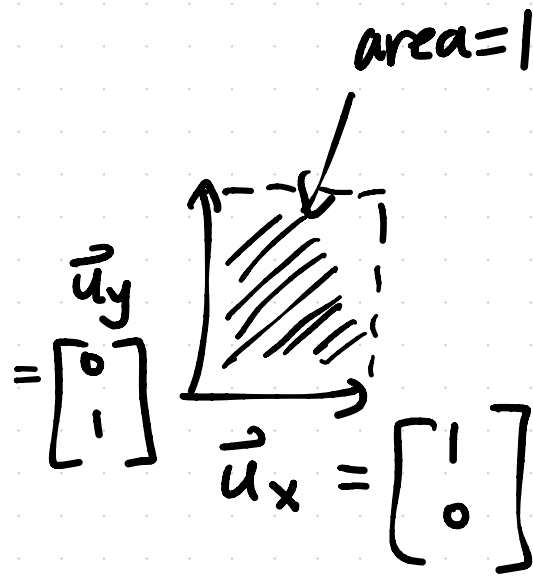
Inverses

Suppose A is an $n \times n$ ^{square} matrix
that is invertible

$\Rightarrow$ this means there exists another ^{$n \times n$} matrix
 B such that

$$AB = BA = I = \begin{bmatrix} 1 & & 0 \\ & \ddots & \\ 0 & & 1 \end{bmatrix}$$

B is A 's
"right inverse"



$\det(A) = 0 \Rightarrow A$'s columns are dependent $\Rightarrow A$ not invertible

$A\vec{u}_y$

$A\vec{u}_x$

If A^2 is invertible, prove A is invertible

Three approaches : ① Constructing A 's inverse

② Null spaces

③ Determinant

① Constructing A 's inverse

given A^2 invertible : what does that mean?

means there exists matrix B where

$$A^2 B = B A^2 = I$$

$$\begin{aligned} AAB &= I \quad \textcircled{1} \\ BAA &= I \quad \textcircled{2} \end{aligned}$$

can we use this to find A 's inverse?

in $\textcircled{1}$, $A(AB) = I \rightarrow A^{-1} = AB$

in $\textcircled{2}$, $(BA)A = I \rightarrow A^{-1} = BA$

$\rightarrow$ which is it? AB or BA ?

$\rightarrow$ in general, they are different, but here, $AB = BA$

proof that here, $AB=BA$

start with BA

$$I^{-1} = I$$

$$BA = BA I = \underbrace{BAA}_{= I, \text{ from last slide}} \underbrace{AB}_{\text{also } I!} = I AB = AB \quad \checkmark$$

$$\text{so, } A^{-1} = AB = BA$$

② Null spaces

if A^2 invertible, then A is invertible

start by assuming the statement isn't true,

assume A^2 invertible but A isn't

→ if A isn't invertible, then
there exists some $\vec{x} \neq \vec{0}$ where

$$A\vec{x} = \vec{0}$$

→ but then $AA\vec{x} = A\vec{0} = \vec{0} \rightarrow A^2\vec{x} = \vec{0}$
→ contradiction since we assumed A^2 inv.

recall,

rank

+

dim nullsp

=

cols

③ Determinants

A^2 invertible $\rightarrow A$ invertible

if A^2 invertible, $\det(A^2) \neq 0$

$$\det(A^2) \neq 0$$

$$\det(AA) \neq 0$$

$$\det(A) \det(A) \neq 0$$

$$[\det(A)]^2 \neq 0$$

$$\det(A) \neq 0 \rightarrow A \text{ is invertible}$$

$$\det(AB) = \det(A)\det(B)$$

$$\det(A+B) \neq \det(A) + \det(B)$$

if $A \begin{bmatrix} 3 \\ 1 \\ -1 \end{bmatrix} = \begin{bmatrix} 9 \\ 4 \\ 3 \end{bmatrix}$ and $A \underbrace{\begin{bmatrix} 4 \\ 0 \\ 2 \end{bmatrix}}_{\text{lin comb of } A\text{'s cols}} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}.$

is A invertible?

no! $\begin{bmatrix} 4 \\ 0 \\ 2 \end{bmatrix} \in \text{nullsp}(A)$, which
means $\dim(\text{nullsp}(A)) \geq 1$,
means $\text{rank}(A) \leq 2$

Unit vector $\vec{u}$

consider the equation

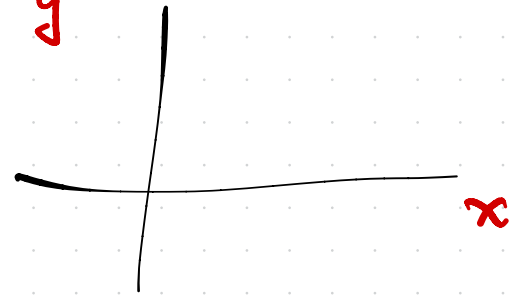
$$\vec{u} \cdot \vec{x} = 0$$

= line $y = -\frac{3}{4}x$

e.g. $\vec{u} = \begin{bmatrix} 3/5 \\ 4/5 \end{bmatrix}$

$$\frac{3}{5}x + \frac{4}{5}y = 0$$

$$y = -\frac{3}{4}x$$



Line $\vec{u} \cdot \vec{x} = 0$

$$P = I - 2 \vec{u} \vec{u}^T$$

Householder
"reflection
matrix"

$n \times n$ matrix $n \times n$ matrix

$P\vec{x}$ is the reflection of $\vec{x}$ across the line/plane/

$$\vec{u} \cdot \vec{x} = 0$$

P is orthogonal! $PP^T = P^TP = I$

equivalent to

$$P^{-1} = P^T$$

also, $P^T = P \Rightarrow P^{-1} = P^T = P \Rightarrow P$ is its own inverse!

$$\begin{aligned}
 P^T P &= \underbrace{(I - 2\vec{u}\vec{u}^T)^T}_{P^T} (I - 2\vec{u}\vec{u}^T) \\
 &= (I^T - 2(\underbrace{\vec{u}\vec{u}^T}_{P^T})^T) (I - 2\vec{u}\vec{u}^T) \\
 &= \underbrace{(I - 2\vec{u}\vec{u}^T)}_P (I - 2\vec{u}\vec{u}^T)
 \end{aligned}$$

$$= I - 2\vec{u}\vec{u}^T - 2\vec{u}\vec{u}^T + 4\underbrace{\vec{u}\vec{u}^T\vec{u}\vec{u}^T}_{=1^2}$$

$$= I \quad \checkmark$$

$$\begin{aligned}
 (AB)^T &= B^T A^T
 \end{aligned}$$

$$\begin{aligned}
 (\vec{u}\vec{u}^T)^T &= (\vec{u}^T)^T \vec{u}^T \\
 &= \vec{u}\vec{u}^T
 \end{aligned}$$

orthogonal matrix $Q \in \mathbb{R}^{n \times n}$

$$\|Q \vec{x}\| = \|\vec{x}\|$$

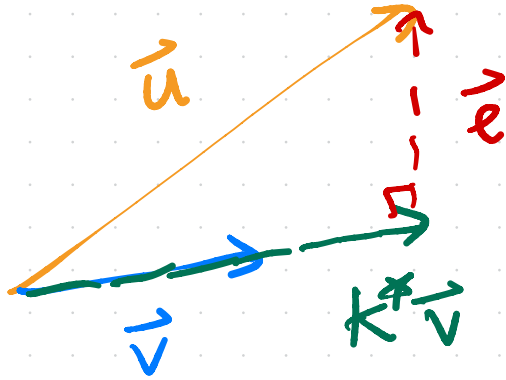
orthogonal matrices preserve length!
only change direction

$$A \vec{x} = \vec{b}$$

$$\vec{x} = A^{-1} \vec{b}$$

Projection S

"the approximation problem"



choose k^* such that

$$\vec{e} = \vec{u} - k^* \vec{v}$$

orthogonal to $\vec{v}$

Consider the vectors

$$\vec{x}^{(1)}, \vec{x}^{(2)}, \dots, \vec{x}^{(d)} \in \mathbb{R}^n$$

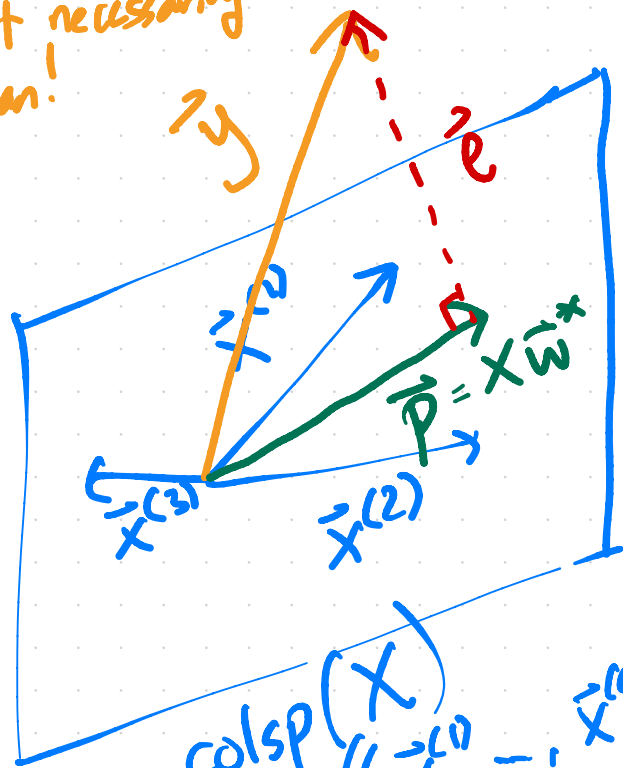
Among all vectors in

$$\text{span}(\vec{x}^{(1)}, \dots, \vec{x}^{(d)})$$

which is closest to $\vec{y}$?

↙ this span is a subspace of $\mathbb{R}^n$

$\vec{y}$ not necessarily
in span!



$\text{colsp}(X)$
 $= \text{span}(\{ \vec{x}^{(1)}, \dots, \vec{x}^{(d)} \})$
 $= \text{a subspace of } \mathbb{R}^n$

$$X = \begin{bmatrix} \underbrace{\vec{x}^{(1)}}_{\text{in } \mathbb{R}^n} & \vec{x}^{(2)} & \dots & \vec{x}^{(d)} \end{bmatrix}_{n \times d}$$

vectors in $\text{colsp}(X)$
 are of the
 form

$$X \vec{w}, \text{ where } \vec{w} \in \mathbb{R}^d$$

of all $X \vec{w}$'s, which is
 closest to $\vec{y}$?

choose $\vec{w}^*$ so that

$$\vec{e} = \vec{y} - X\vec{w}^*$$

is orthogonal to

$\text{colsp}(X)$

(equivalent to being orthogonal to
each of X 's columns)

choose

$\vec{w}$

so that

$$\vec{X}^{(1)} \cdot (\vec{y} - X\vec{w}) = 0$$

$$\vdots$$
$$\vec{X}^{(d)} \cdot (\vec{y} - X\vec{w}) = 0$$

$$X^T (\vec{y} - X\vec{w}) = \vec{0} = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$